



Robot Cop

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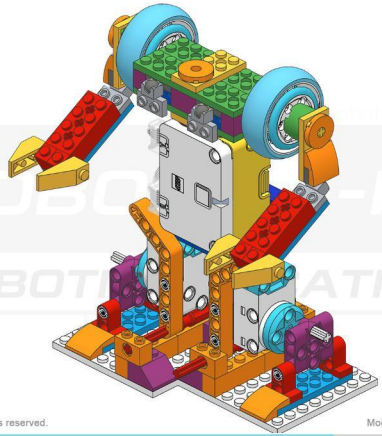
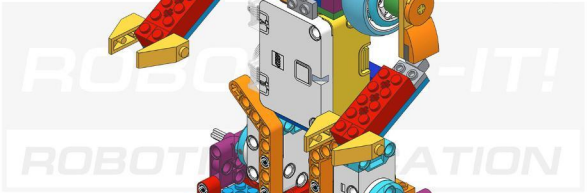
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PRIME



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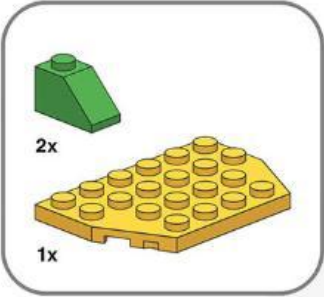
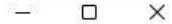


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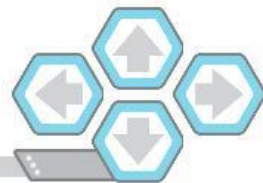
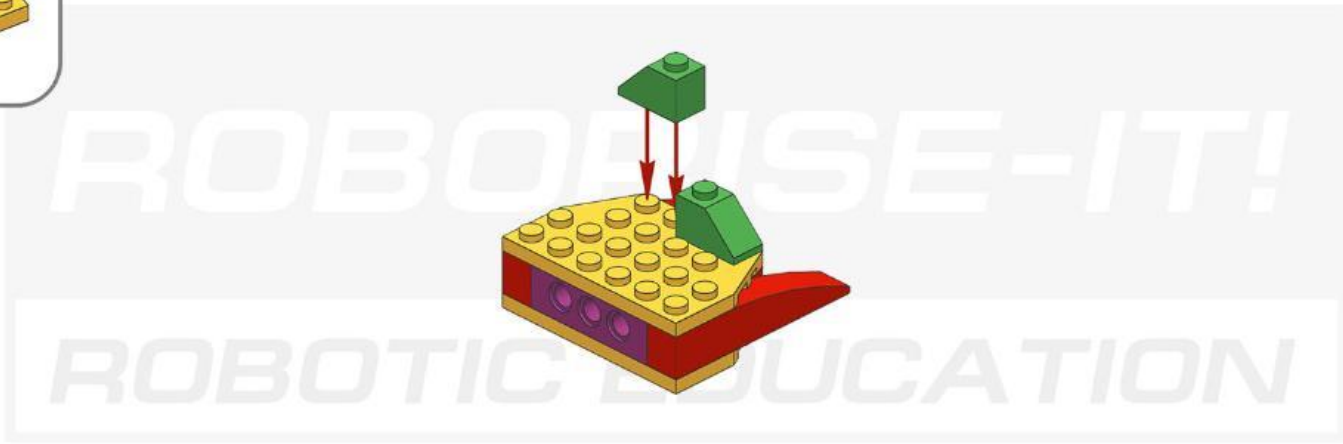
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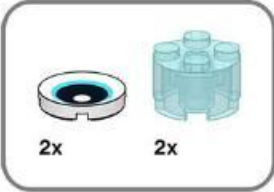
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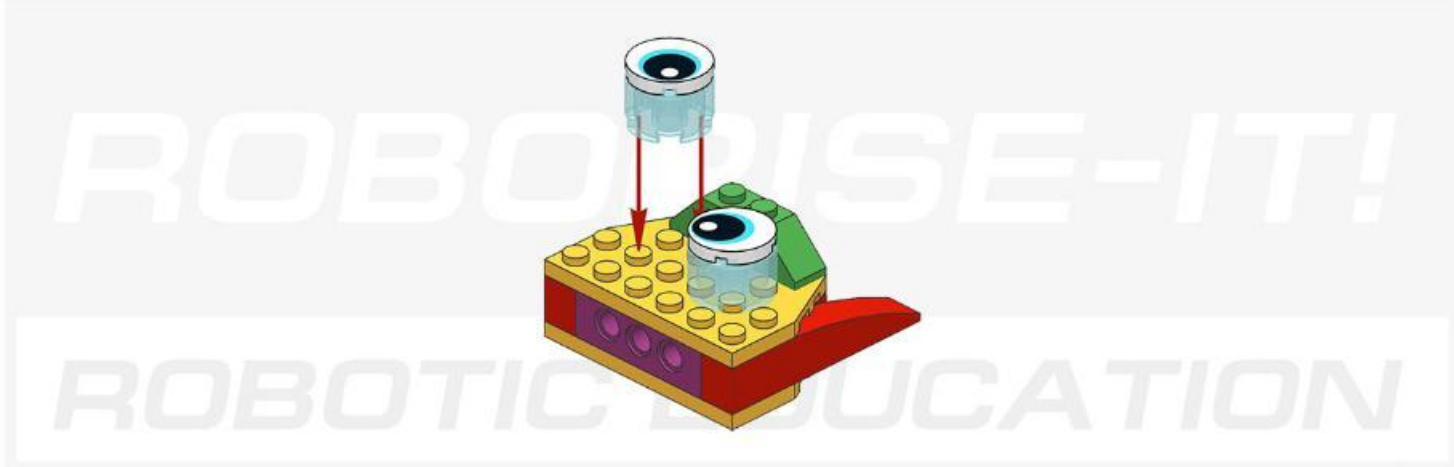
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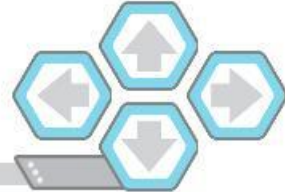
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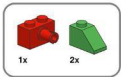
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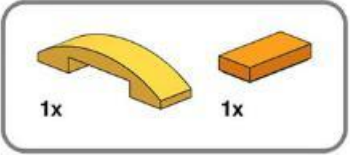
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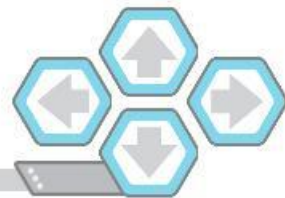
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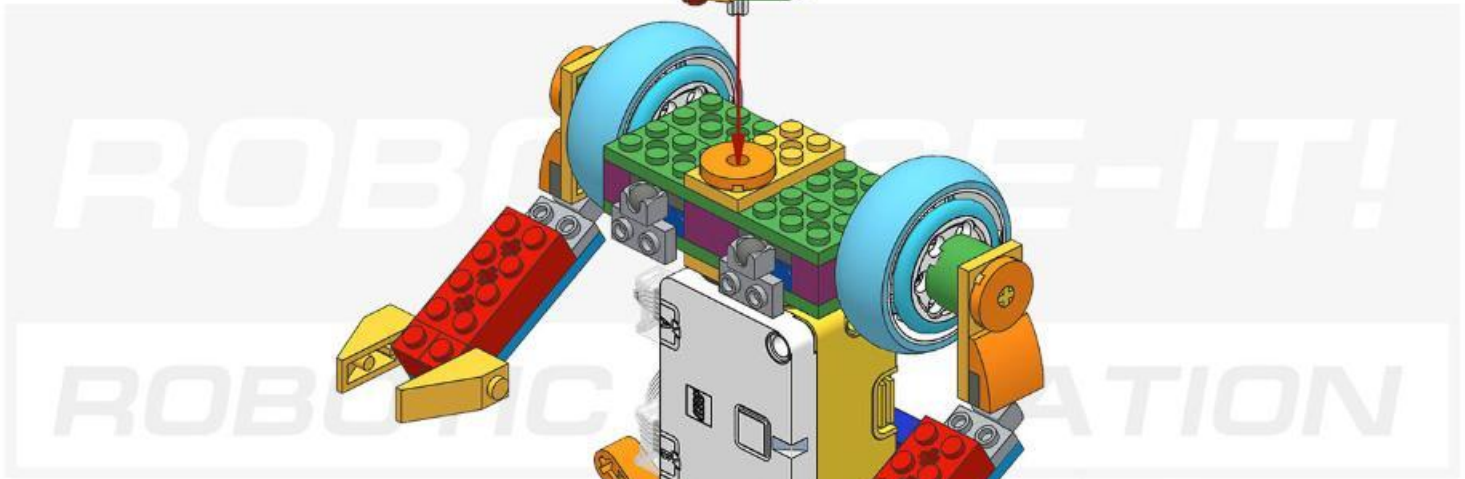
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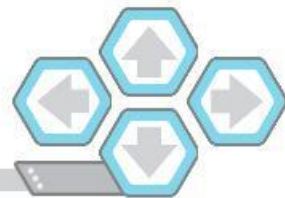
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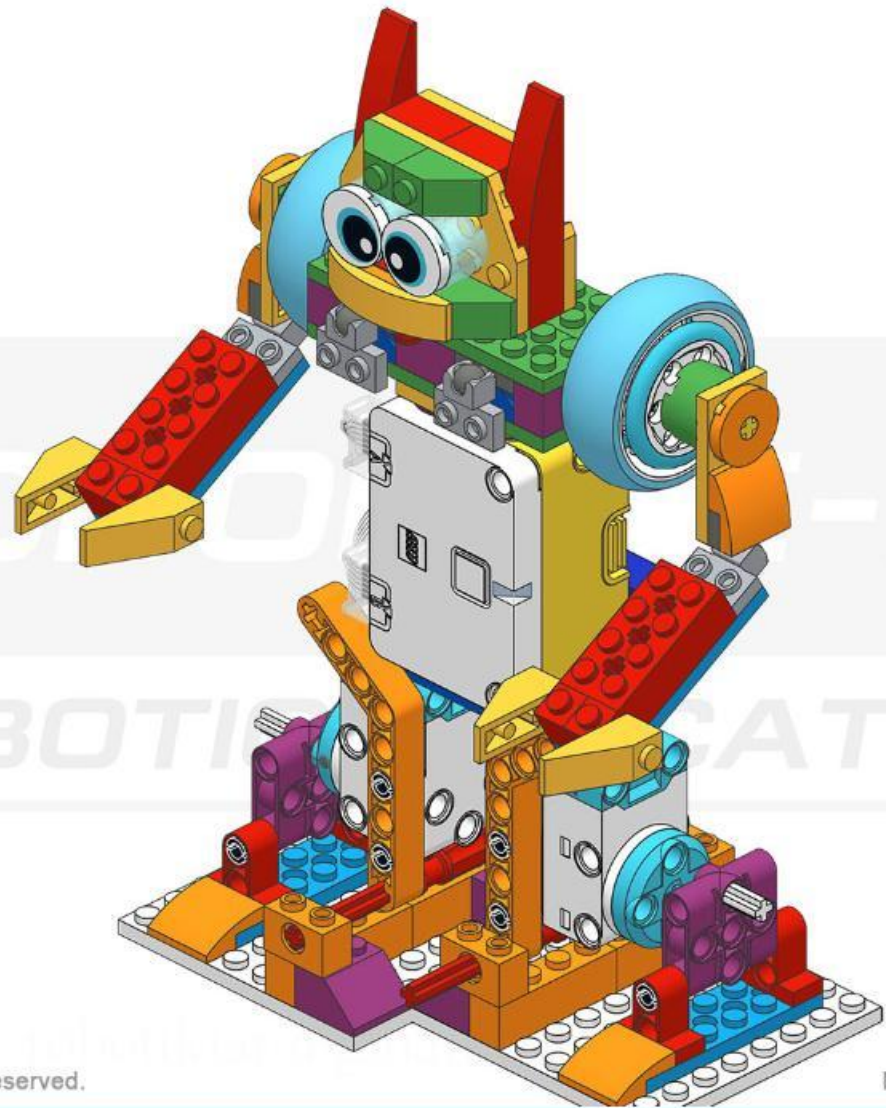




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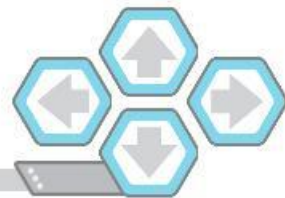
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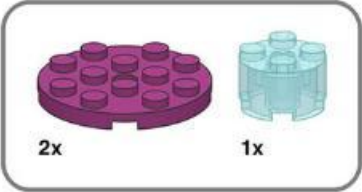
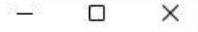
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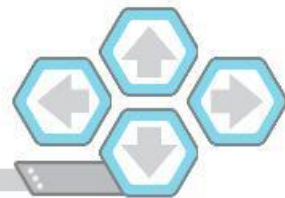
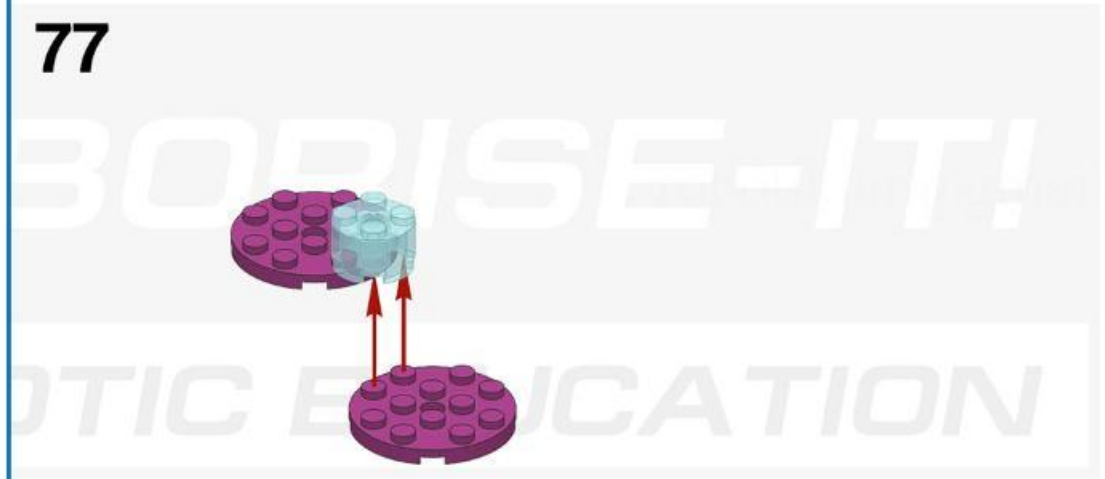
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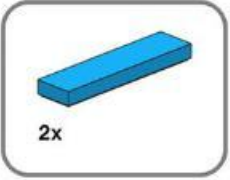
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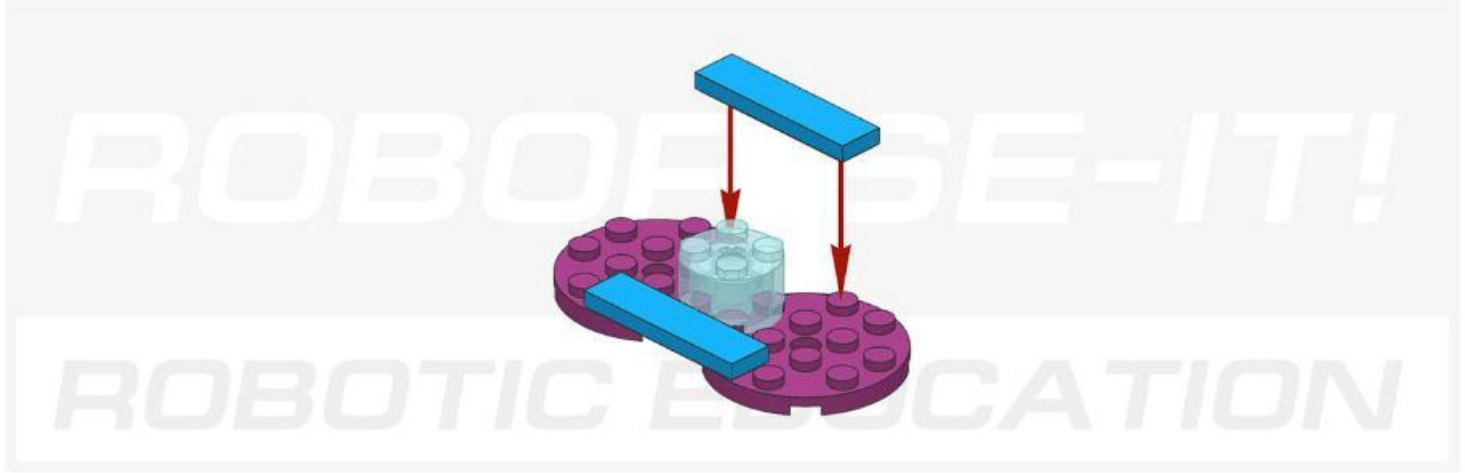
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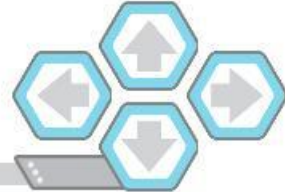
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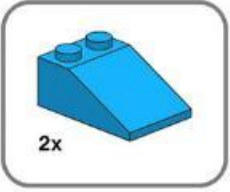
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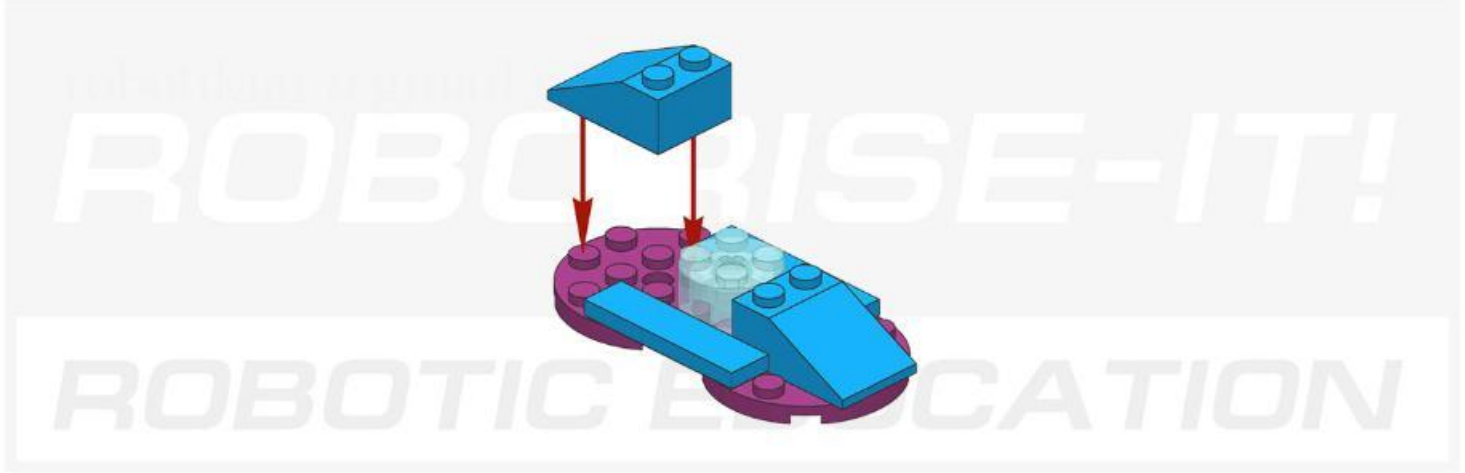
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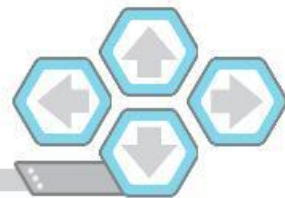
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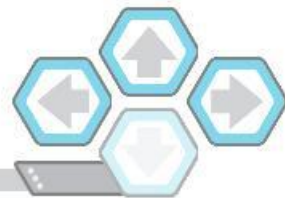
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Task 3*. Program 2

Algorithm

Program

If you have enough time, you can create a block for moving the robot forward yourself based on the program you wrote to move the robot forward:

```
define 0-Walk distance cm  
  set Center Button light to   
  A go shortest path to position 90  
  B go shortest path to position 90  
  set movement speed to 50 %  
  move ↑ for distance cm
```

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