



Robot Cop

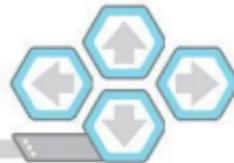
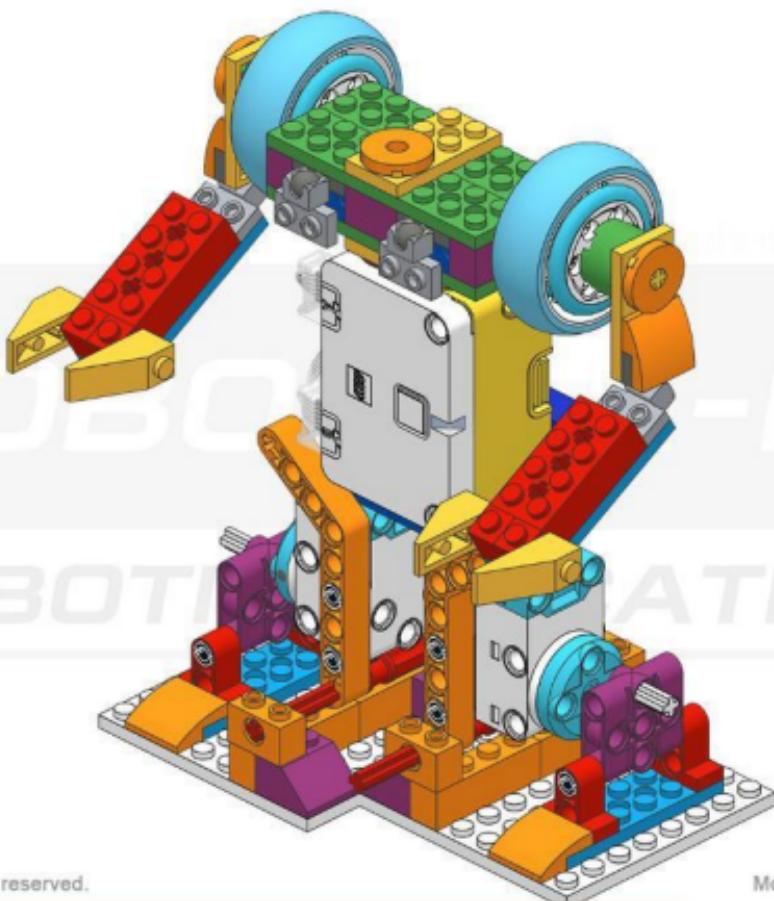
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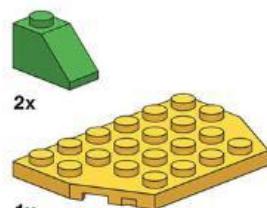


PRIME

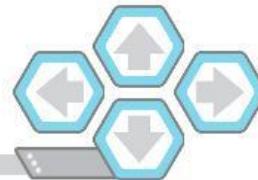
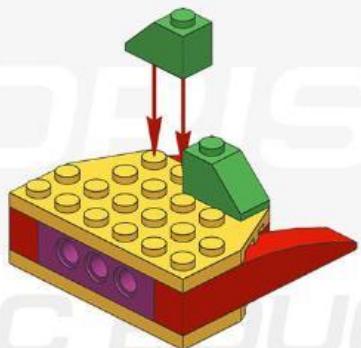


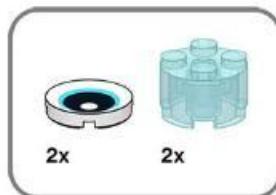
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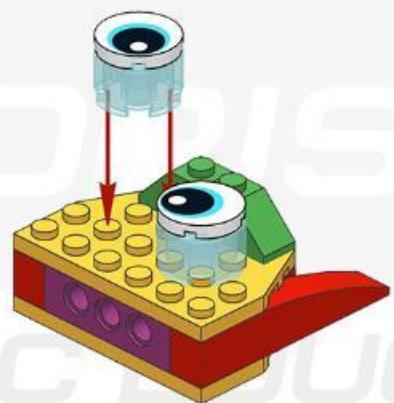
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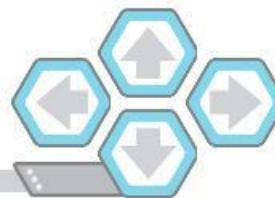
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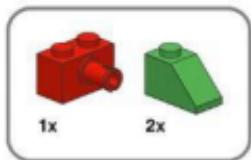
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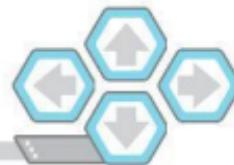


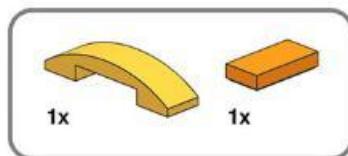
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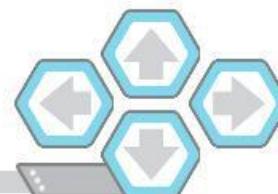
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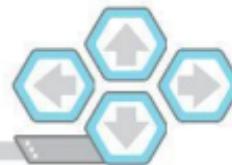


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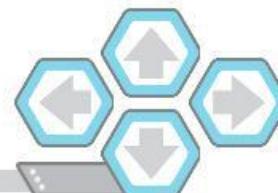
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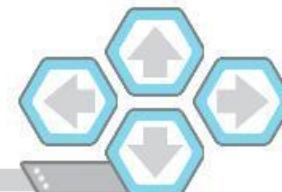
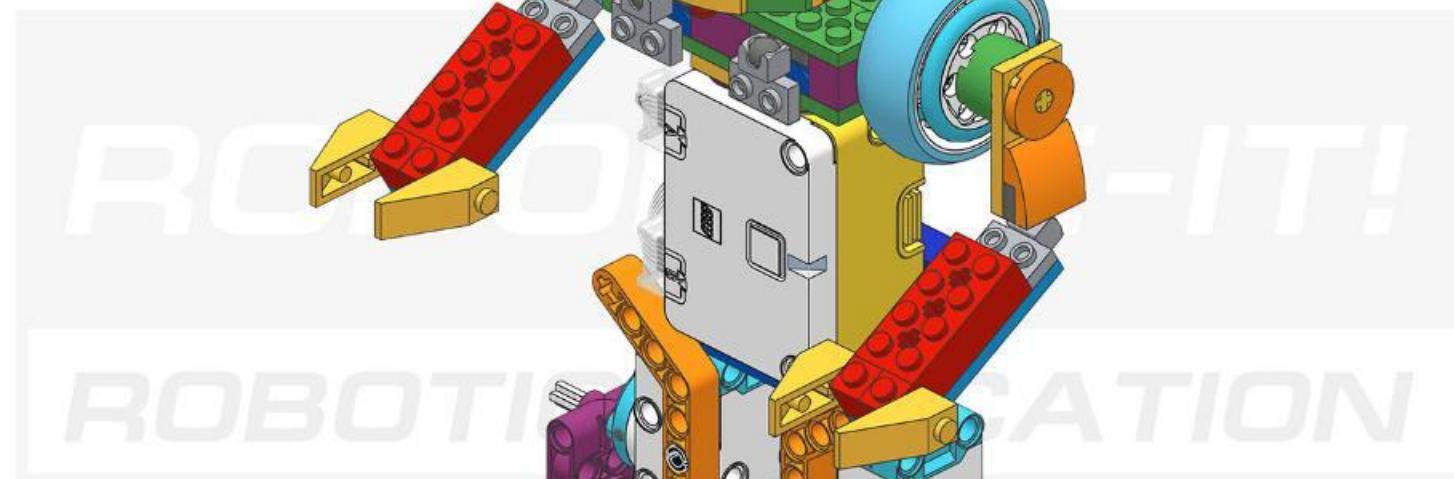
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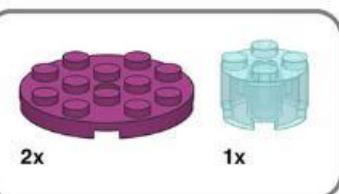
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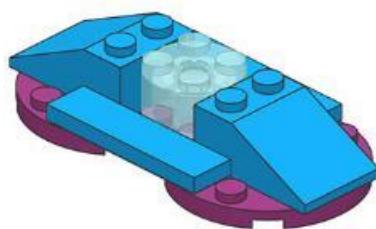
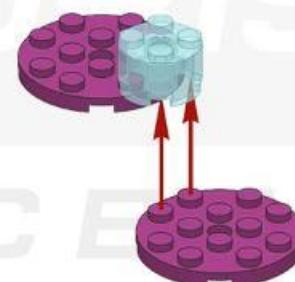
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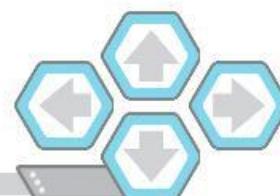
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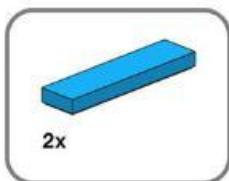


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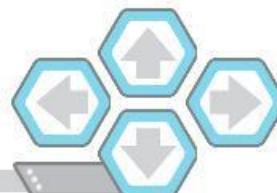
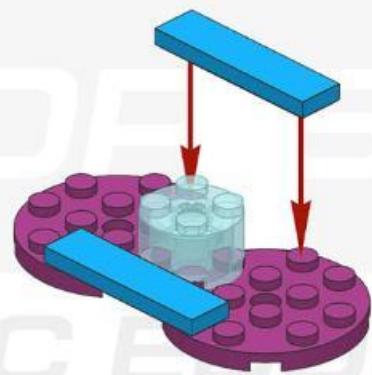
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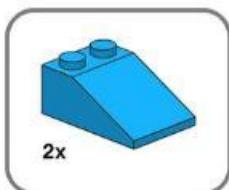
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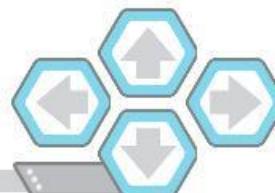
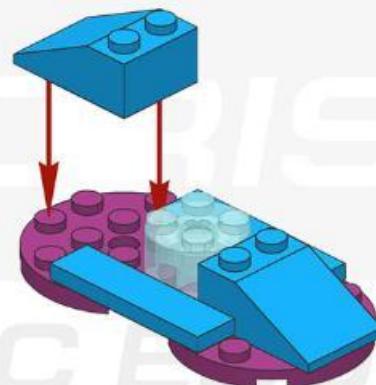


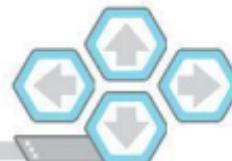
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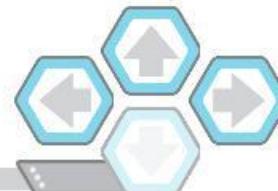
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Task 3*. Program 2

Algorithm

Program

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If you have enough time, you can create a block for moving the robot forward yourself based on the program you wrote to move the robot forward:

```
define [0-Walk : distance : cm]
  [set Center Button light to green v]
  [A : go : shortest path : to position : 90]
  [B : go : shortest path : to position : 90]
  [set movement speed to : 50 : %]
  [move : up : for : distance : cm : -]
end
```

